

# UNIT WISE PRACTICE QUESTION PAPER

## MARKING SCHEME CLASS XII

### MATHEMATICS(CODE-041)

CHAPTER/UNITS: DIFFERENTIAL EQUATION, VECTOR AND 3D GEOMETRY

#### SECTION:A

(Solution of MCQs of 1 Mark each)

Q.NO.	ANS	SOLUTION
1.	(C)	<p>Given: <math> \vec{a} \cdot \vec{b} ^2 +  \vec{a} \times \vec{b} ^2 = 144</math> &amp; <math> \vec{a}  = 4</math></p> <p>By Langrange's identity, <math> \vec{a} \cdot \vec{b} ^2 +  \vec{a} \times \vec{b} ^2 =  \vec{a} ^2  \vec{b} ^2</math></p> $\Rightarrow 144 = 4^2  \vec{b} ^2$ $\Rightarrow  \vec{b} ^2 = 9$ $\Rightarrow  \vec{b}  = 3$
2.	(A)	<p>Given: <math>\sqrt{3}\vec{a} - \vec{b}</math> is an unit vector</p> $\Rightarrow  \sqrt{3}\vec{a} - \vec{b}  = 1$ <p>Squaring on both sides, <math> \sqrt{3}\vec{a} - \vec{b} ^2 = 1</math></p> $\Rightarrow  \sqrt{3}\vec{a} ^2 - 2\sqrt{3}\vec{a} \cdot \vec{b} +  \vec{b} ^2 = 1$ $\Rightarrow  \sqrt{3} ^2  \vec{a} ^2 - 2\sqrt{3} \vec{a}  \vec{b} \cos\theta +  \vec{b} ^2 = 1$ $\Rightarrow 3 - 2\sqrt{3}\cos\theta + 1 = 1 \quad (\text{since }  \vec{a}  = 1 \text{ \& }  \vec{b}  = 1)$ $\therefore \cos\theta = \frac{\sqrt{3}}{2} \Rightarrow \theta = \frac{\pi}{6} = 30^\circ$
3.	(A)	<p>Given: <math> \vec{a} + \vec{b}  =  \vec{a} - \vec{b} </math></p> <p>Squaring on both sides, <math> \vec{a} + \vec{b} ^2 =  \vec{a} - \vec{b} ^2</math></p> $\Rightarrow  \vec{a} ^2 +  \vec{b} ^2 + 2\vec{a} \cdot \vec{b} =  \vec{a} ^2 +  \vec{b} ^2 - 2\vec{a} \cdot \vec{b}$ $\Rightarrow 4\vec{a} \cdot \vec{b} = 0$ $\Rightarrow 4 \vec{a}  \vec{b} \cos\theta = 0$ $\therefore \cos\theta = 0 \Rightarrow \theta = 90^\circ$

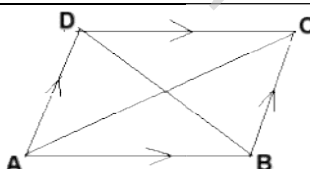
4		<p>Given: <math>\vec{a} = 2\hat{i} + 3\hat{j} + \lambda\hat{k}</math> and <math> -5\vec{a}  = 25</math></p> <p><math>\Rightarrow  -5  \vec{a}  = 25</math></p> <p><math>\Rightarrow 5\sqrt{2^2 + 3^2 + \lambda^2} = 25</math></p> <p><math>\Rightarrow \sqrt{13 + \lambda^2}</math></p> <p><math>\Rightarrow 13 + \lambda^2 = 25 \Rightarrow \lambda^2 = 12 \Rightarrow \lambda = \pm 2\sqrt{3}</math></p>
5	(D)	<p>Given: <math>2\hat{i} - \hat{j} + 2\hat{k}</math> and <math>3\hat{i} + \lambda\hat{j} + \hat{k}</math> are perpendicular</p> <p><math>\Rightarrow (2\hat{i} - \hat{j} + 2\hat{k}) \cdot (3\hat{i} + \lambda\hat{j} + \hat{k}) = 0</math></p> <p><math>\Rightarrow 2 \cdot 3 - 1 \cdot \lambda + 2 \cdot 1 = 0</math></p> <p><math>\Rightarrow 6 - \lambda + 2 = 0</math></p> <p><math>\Rightarrow \lambda = 8</math></p>
6	(D)	<p>Given: <math>\vec{AB} = 2\hat{i} + \hat{j} - 3\hat{k}</math> and A (1, 2, -1)</p> <p><math>\Rightarrow</math> p.v. of B - p.v. of A = <math>2\hat{i} + \hat{j} - 3\hat{k}</math></p> <p><math>\Rightarrow</math> p.v. of B - (<math>\hat{i} + 2\hat{j} - \hat{k}</math>) = <math>2\hat{i} + \hat{j} - 3\hat{k}</math></p> <p><math>\Rightarrow</math> p.v. of B = <math>3\hat{i} + 3\hat{j} - 4\hat{k}</math></p>
7	(A)	<p>Given: <math>(1 - y^2) \frac{dx}{dy} + yx = ay</math></p> <p><math>\Rightarrow \frac{dx}{dy} + \frac{y}{(1 - y^2)}x = \frac{ay}{(1 - y^2)}</math>, which is in the form of <math>\frac{dx}{dy} + Px = Q</math></p> <p><math>\therefore</math> I. F. = <math>e^{\int P dy} = e^{\int \frac{y}{1 - y^2} dy}</math></p> <p><math>= e^{\frac{-1}{2} \int \frac{-2y}{1 - y^2} dy}</math></p> <p><math>= e^{\frac{-1}{2} \log(1 - y^2)}</math></p> <p><math>= e^{\log(1 - y^2)^{\frac{-1}{2}}}</math></p> <p><math>= (1 - y^2)^{\frac{-1}{2}} = \frac{1}{\sqrt{1 - y^2}}</math></p>
8	(C)	<p><math>y = Ax + A^3</math> is corresponds to the D.E. of order one as it is involved only one arbitrary constant i.e. A</p>
9	(D)	<p><math>1 + \left(\frac{d^3y}{dx^3}\right)^2</math></p> <p><math>= \left(\frac{d^2y}{dx^2}\right)^{\frac{3}{2}}</math></p>

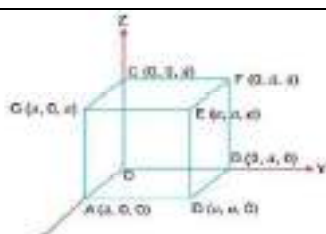
10	(B)	<p>Concept: Solution of a D.E. under an initial given condition is a particular solution.</p> <p>And, a particular solution of a D.E. of order one and degree one have only one solution.</p> <p>Explanation:</p> <p>Given: <math>\frac{dy}{dx} = \frac{y+1}{x-1}</math> when <math>y(1)=2</math> (initial condition)</p> $\Rightarrow \frac{1}{y+1} dy = \frac{1}{x-1} dx \Rightarrow \int \frac{1}{y+1} dy = \int \frac{1}{x-1} dx \Rightarrow \log(y+1) = \log(x-1) + C$ $\Rightarrow \log(y+1) - \log(x-1) = C$ $\Rightarrow \log\left(\frac{y+1}{x-1}\right) = \log A$ $\Rightarrow \frac{y+1}{x-1} = A$ $\Rightarrow y+1 = A(x-1) \dots \dots \dots (i)$ <p>But, when <math>x=1, y=2</math> ; (i) <math>\Rightarrow 2+1 = A(0-1) \Rightarrow A = -3</math></p> <p>Hence, from (i), the P.S. is <math>y+1 = -3(x-1)</math></p> $\Rightarrow y+3x = 2$
11	(D)	<p>Here, in option (D) the degree of <math>x</math> and <math>y</math> not defined.</p> <p>A homogeneous function is a function that has the same degree of the polynomial in each variables. Homogeneous function of <math>x</math> and <math>y</math> is a function that can be expressed in the form of either <math>f\left(\frac{x}{y}\right)</math> or <math>f\left(\frac{y}{x}\right)</math>.</p>
12	(C)	<p>Given: <math>\frac{dx}{x} + \frac{dy}{y} = 0</math></p> $\Rightarrow \frac{1}{x} dx$ $\Rightarrow \int \frac{1}{x} dx$ $+ \int \frac{1}{y} dy$ $\Rightarrow \log x$ $\Rightarrow \log xy$ $\Rightarrow xy = C$

13	(D)	<p>Given: <math>\frac{x-1}{2} = \frac{1-y}{3} = \frac{2z-1}{12}</math></p> <p>Standard form: <math>\frac{x-1}{2} = \frac{y-1}{-3} = \frac{z-\frac{1}{2}}{6}</math></p> <p>Direction ratios are: <math>\langle 2, -3, 6 \rangle</math></p> <p>Direction cosines are: <math>\langle \frac{2}{\sqrt{2^2+(-3)^2+6^2}}, \frac{-3}{\sqrt{2^2+(-3)^2+6^2}}, \frac{6}{\sqrt{2^2+(-3)^2+6^2}} \rangle</math></p> <p>i.e. <math>\langle \frac{2}{7}, \frac{-3}{7}, \frac{6}{7} \rangle</math></p>
14	(C)	<p>The x and z co-ordinates of a point on y-axis are 0.</p> <p>Therefore, required point on the y-axis = (0,-3,0)</p>
15	(B)	<p>We know that <math>\cos^2\alpha + \cos^2\beta + \cos^2\gamma = 1</math></p> <p>Now, <math>\cos 2\alpha + \cos 2\beta + \cos 2\gamma = (2\cos^2\alpha - 1) + (2\cos^2\beta - 1) + (2\cos^2\gamma - 1)</math></p> <p><math>= 2(\cos^2\alpha + \cos^2\beta + \cos^2\gamma) - 3</math></p> <p><math>= -1</math></p>
16	(D)	<p>The required distance is the distance of P(a,b,c) from Q(0,b,0)</p> <p><math>= \sqrt{a^2 + c^2}</math></p>
17	(A)	<p>Direction ratios of the through (1, -1, 2) &amp; (3, 4, -2) are <math>\langle 2, 5, -4 \rangle</math></p> <p>Direction ratios of the through (<math>\lambda, 3, 2</math>) &amp; (3, 5, 6) are <math>\langle 3 - \lambda, 2, 4 \rangle</math></p> <p>Since, the lines are perpendicular we have</p> <p><math>a_1a_2 + b_1b_2 + c_1c_2 = 0</math></p> <p><math>\Rightarrow 2(3 - \lambda) + 5 \cdot 2 + (-4) \cdot 4 = 0</math></p> <p><math>\Rightarrow 6 - 2\lambda + 10 - 16 = 0</math></p> <p><math>\Rightarrow \lambda = 0</math></p>
18	(B)	<p>Given lines: <math>\frac{1-x}{3} = \frac{7y-14}{2p} = \frac{z-3}{2}</math> and <math>\frac{7-7x}{3p} = \frac{y-5}{1} = \frac{6-z}{5}</math></p> <p>Standard forms of the lines: <math>\frac{x-1}{-3} = \frac{y-2}{\frac{2p}{7}} = \frac{z-3}{2}</math> and <math>\frac{x-1}{-\frac{3p}{7}} = \frac{y-5}{1} = \frac{z-6}{-5}</math></p> <p>Since, the lines are perpendicular we have</p> <p><math>a_1a_2 + b_1b_2 + c_1c_2 = 0</math></p> <p><math>\Rightarrow -3 \cdot (-\frac{3p}{7}) + \frac{2p}{7} \cdot 1 + 2 \cdot (-5) = 0</math></p> <p><math>\Rightarrow \frac{11p}{7} = 10</math></p> <p><math>\Rightarrow p = \frac{70}{11}</math></p>
19	(C)	<p>The assertion(A) is true as, for the Cartesian equation <math>\frac{x-x_1}{a} = \frac{y-y_1}{b} = \frac{z-y_1}{c}</math>, the vector equation is <math>\vec{r} = x_1\hat{i} + y_1\hat{j} + y_1\hat{k} + \lambda(a\hat{i} + b\hat{j} + c\hat{k})</math>.</p> <p>The reason (R) is not true because the correct equation of the line</p>



	<p>Given <math>\vec{a}</math> = p.v. of B = <math>\vec{AB} = \hat{j} + \hat{k}</math> and <math>\vec{b}</math> = p.v. of C = <math>\vec{AC} = 3\hat{i} - \hat{j} + 4\hat{k}</math></p> <p><math>\therefore</math> Median <math>\vec{AD} = \vec{d}</math> i.e. by mid point formula, <math>\vec{d} = \frac{\vec{a} + \vec{b}}{2}</math></p> $= \frac{3}{2}\hat{i} + 0\hat{j} + \frac{5}{2}\hat{k}$ <p><math>\therefore</math> Length of the median <math>\vec{AD} =  \vec{d}  = \sqrt{\left(\frac{3}{2}\right)^2 + 0^2 + \left(\frac{5}{2}\right)^2} = \frac{\sqrt{34}}{2}</math></p>	<p>1</p> <p><math>\frac{1}{2}</math></p>
22.	<p>By section formula, position vector of R = <math>\frac{2(2\vec{a} + \vec{b}) - 1(\vec{a} - 3\vec{b})}{2 - 1} = 3\vec{a} + 5\vec{b}</math></p> <p>Again, mid-point of <math>RQ = \frac{(3\vec{a} + 5\vec{b}) + (\vec{a} - 3\vec{b})}{2} = 2\vec{a} + \vec{b}</math> = Position vector of P. Hence, P is the mid-point of RQ</p>	<p>1</p> <p>1</p>
22. (OR)	<p>The vector of magnitude 9 unit perpendicular to both the vectors <math>\hat{i} - \hat{j}</math> and <math>\hat{i} + \hat{j}</math></p> $= 9 \cdot \frac{[(\hat{i} - \hat{j}) \times (\hat{i} + \hat{j})]}{[(\hat{i} - \hat{j}) \times (\hat{i} + \hat{j})]}$ $= 9 \cdot \frac{[\hat{i} \times \hat{i} + \hat{i} \times \hat{j} - \hat{j} \times \hat{i} - \hat{j} \times \hat{j}]}{[\hat{i} \times \hat{i} + \hat{i} \times \hat{j} - \hat{j} \times \hat{i} - \hat{j} \times \hat{j}]}$ $= 9 \cdot \frac{[0 + \hat{k} - (-\hat{k}) - 0]}{[0 + \hat{k} - (-\hat{k}) - 0]} \text{ by right handed system}$ $= 9 \cdot \left[ \frac{2\hat{k}}{2\hat{k}} \right] = 9\hat{k} \quad (\text{since }  2\hat{k}  = 2 \hat{k}  = 2)$	<p>1</p> <p><math>\frac{1}{2}</math></p> <p><math>\frac{1}{2}</math></p>

23.	<p>Given: <math>\frac{dy}{dx} = e^{x-y} + x^2 e^{-y}</math></p> $\Rightarrow \frac{dy}{dx} = \frac{e^x}{e^y} + \frac{x^2}{e^y}$ $\Rightarrow e^y \frac{dy}{dx} = (e^x + x^2) dx$ $\Rightarrow \int e^y dy = \int (e^x + x^2) dx$ $\Rightarrow e^y = e^x + \frac{x^3}{3} + C$	$\frac{1}{2}$  1  $\frac{1}{2}$
24.	<p>Given that: <math>\frac{dy}{dx} = ye^x</math> and <math>x=0, y=e</math></p> $\Rightarrow \frac{1}{y} dy = e^x dx \text{ (variables separation)}$ $\Rightarrow \int \frac{1}{y} dy = \int e^x dx$ $\Rightarrow \log y = e^x + C \dots \dots \dots (i)$ <p>But <math>y = e</math> when <math>x = 0</math>, (i) gives <math>\log e = e^0 + C \Rightarrow 1 = 1 + C \Rightarrow C = 0</math></p> <p>From (i), now <math>\log y = e^x</math></p> <p>When <math>x = 1</math>,</p> $\log y = e^1 = e \Rightarrow y = e^e$	$\frac{1}{2}$  $\frac{1}{2}$  1
25	<p>Given lines: <math>\vec{r} = 3\hat{i} - 2\hat{j} + 6\hat{k} + \lambda(2\hat{i} + \hat{j} + 2\hat{k})</math> and <math>\vec{r} = 2\hat{j} - 5\hat{k} + \mu(6\hat{i} + 3\hat{j} + 2\hat{k})</math></p> <p>Direction ratios of the line are <math>\langle 2, 1, 2 \rangle</math> and <math>\langle 6, 3, 2 \rangle</math></p> <p>If <math>\theta</math> is an angle between the lines, then</p> $\cos \theta = \frac{2 \cdot 6 + 1 \cdot 3 + 2 \cdot 2}{\sqrt{2^2 + 1^2 + 2^2} \sqrt{6^2 + 3^2 + 2^2}} = \frac{19}{\sqrt{9} \sqrt{49}} = \frac{19}{21}$ $\therefore \theta = \cos^{-1} \left( \frac{19}{21} \right)$	1  1
	<p style="text-align: center;"><b>SECTION C</b> (Each question carries 3 marks)</p>	
26	 <p>Let the parallelogram be ABCD with</p> $\vec{AB} = \vec{DC} = 2\hat{i} - 4\hat{j} - 5\hat{k} \text{ and } \vec{AD} = \vec{BC} = 2\hat{i} + 2\hat{j} + 3\hat{k}$ <p>Now, <math>\vec{d}_1 = \vec{AC} = \vec{AB} + \vec{BC} = (2\hat{i} - 4\hat{j} - 5\hat{k}) + (2\hat{i} + 2\hat{j} + 3\hat{k}) = 4\hat{i} - 2\hat{j} - 2\hat{k}</math></p> $\vec{d}_2 = \vec{BD} = -\vec{AB} + \vec{AD} = -(2\hat{i} - 4\hat{j} - 5\hat{k}) + (2\hat{i} + 2\hat{j} + 3\hat{k}) = 0\hat{i} + 6\hat{j} + 8\hat{k}$ <p>Also, <math> \vec{d}_1  = \sqrt{4^2 + 2^2 + (-2)^2} = \sqrt{24}</math> and <math> \vec{d}_2  = \sqrt{0^2 + 6^2 + 8^2} = \sqrt{100} = 10</math></p>	1  1  1

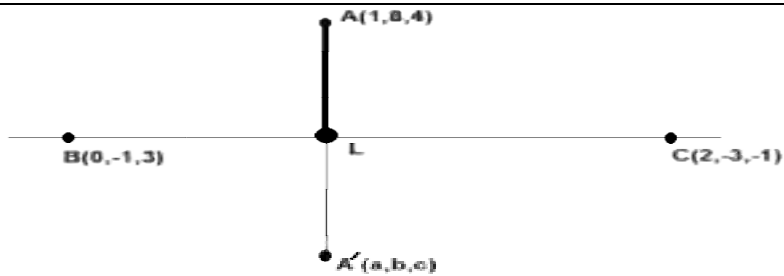
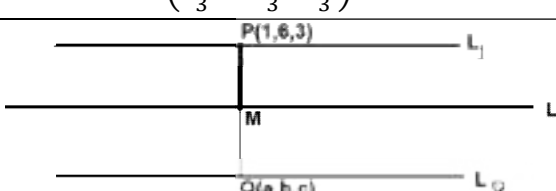
	<p>Thus, <math>\widehat{d_1} = \frac{\vec{d_1}}{ \vec{d_1} } = \frac{4\hat{i}-2\hat{j}-2\hat{k}}{\sqrt{24}}</math> and <math>\widehat{d_2} = \frac{\vec{d_2}}{ \vec{d_2} } = \frac{6\hat{j}+8\hat{k}}{10}</math></p> <p>Area of parallelogram = <math>\frac{1}{2} \vec{d_1} \times \vec{d_2}  = \frac{1}{2} \begin{vmatrix} \hat{i} &amp; \hat{j} &amp; \hat{k} \\ 4 &amp; -2 &amp; -2 \\ 0 &amp; 6 &amp; 8 \end{vmatrix} =</math></p> <p><math>\frac{1}{2} -4\hat{i} - 32\hat{j} + 24\hat{k}  = \frac{1}{2}\sqrt{1616}</math></p>	
26. (OR)	<p>Given : A, B, C, D are the points with position vectors <math>\hat{i} + \hat{j} - \hat{k}</math>, <math>2\hat{i} - \hat{j} + 3\hat{k}</math>, <math>2\hat{i} - 3\hat{k}</math> and <math>3\hat{i} - 2\hat{j} + \hat{k}</math> respectively.</p> <p>Now, <math>\overrightarrow{AB} = p.v. \text{ of } B - p.v. \text{ of } A = (2\hat{i} - \hat{j} + 3\hat{k}) - (\hat{i} + \hat{j} - \hat{k}) = \hat{i} - 2\hat{j} + 4\hat{k}</math></p> <p><math>\overrightarrow{CD} = p.v. \text{ of } D - p.v. \text{ of } C = (3\hat{i} - 2\hat{j} + \hat{k}) - (2\hat{i} - 3\hat{k}) = \hat{i} - 2\hat{j} + 4\hat{k}</math></p> <p>Hence, projection of <math>\overrightarrow{AB}</math> along <math>\overrightarrow{CD} = \frac{\overrightarrow{AB} \cdot \overrightarrow{CD}}{ \overrightarrow{CD} } = \frac{1.1 + (-2).(-2) + 4.4}{\sqrt{1^2 + (-2)^2 + 4^2}} = \frac{21}{\sqrt{21}} = \sqrt{21} \text{sq. units}</math></p>	1 2
27.	<p>Given : <math>\alpha = 60^\circ</math>, <math>\beta = 45^\circ</math></p> <p>We know, <math>\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = 1</math></p> <p><math>\Rightarrow \cos^2 60^\circ + \cos^2 45^\circ + \cos^2 \gamma = 1</math></p> <p><math>\Rightarrow \left(\frac{1}{2}\right)^2 + \left(\frac{1}{\sqrt{2}}\right)^2 + \cos^2 \gamma = 1</math></p> <p><math>\Rightarrow \cos^2 \gamma = 1 - \frac{1}{4} - \frac{1}{2} = \frac{1}{4}</math></p> <p><math>\therefore \cos \gamma = \frac{1}{2} \Rightarrow \gamma = 60^\circ</math></p> <p><math>\therefore l = \cos 60^\circ = \frac{1}{2}, m = \cos 45^\circ = \frac{1}{\sqrt{2}}, n = \cos 45^\circ = \frac{1}{\sqrt{2}}</math></p> <p><math>\therefore \overrightarrow{OA} =  \overrightarrow{OA} (l\hat{i} + m\hat{j} + n\hat{k})</math></p> <p><math>= 10\left(\frac{1}{2}\hat{i} + \frac{1}{\sqrt{2}}\hat{j} + \frac{1}{\sqrt{2}}\hat{k}\right) = 5\hat{i} + 5\sqrt{2}\hat{j} + 5\hat{k}</math></p>	1  1  1
28	 <p>Diagonals are OE, AF, BG, CD.</p> <p>Direction ratios of OE are <math>\langle a - 0, a - 0, a - 0 \rangle</math> i.e. <math>\langle a, a, a \rangle</math></p> <p><math>\therefore</math> direction cosines of OE are</p>	1  1





	$\therefore y.(1+x^2) = \int \frac{1}{(1+x^2)^2} \cdot (1+x^2)dx + C$ $= \int \frac{1}{(1+x^2)} dx + C$ $\therefore y.(1+x^2) = \tan^{-1} x + C \dots\dots(i)$ <p>By question <math>y = 0</math> when <math>x = 1, (i) \Rightarrow 0.(1+1^2) = \tan^{-1} 1 + C \Rightarrow 0 = \frac{\pi}{4} + C \Rightarrow C = -\frac{\pi}{4}</math></p> <p>Hence, the reqd. particular solution is, <math>y.(1+x^2) = \tan^{-1} x - \frac{\pi}{4}</math></p>	1
31.	<p>Given, projection of <math>\vec{b}</math> along <math>\vec{a}</math> = the projection of <math>\vec{c}</math> along <math>\vec{a}</math></p> $\Rightarrow \frac{\vec{b} \cdot \vec{a}}{ \vec{b} } = \frac{\vec{c} \cdot \vec{a}}{ \vec{b} }$ $\Rightarrow \vec{b} \cdot \vec{a} = \vec{c} \cdot \vec{a} \dots\dots(i)$ <p>Also, given <math>\vec{b} \perp \vec{c} \Rightarrow \vec{b} \cdot \vec{c} = 0 \dots\dots(ii)</math></p> <p>Then, <math> 3\vec{a} - 2\vec{b} + 2\vec{c} ^2 = 9 \vec{a} ^2 + 4 \vec{b} ^2 + 4 \vec{c} ^2 - 12\vec{a} \cdot \vec{b} - 8\vec{b} \cdot \vec{c} + 12\vec{c} \cdot \vec{a}</math></p> $= 9.1^2 + 4.2^2 + 4.3^2 - 12\vec{a} \cdot \vec{b} - 0 + 12\vec{a} \cdot \vec{b}, \text{ (by(i) \& (ii))}$ $= 9 + 16 + 36 = 31$	1 1 1
31. (OR)	<p>Let <math>\vec{a} = \hat{i} + \hat{j} + \hat{k}</math>, <math>\vec{b} = 2\hat{i} + 4\hat{j} - 5\hat{k}</math> and <math>\vec{c} = \lambda\hat{i} + 2\hat{j} + 3\hat{k}</math>.</p> <p>According to question, <math> \vec{a} \times \hat{p}  = \sqrt{2}</math>, where</p> $\hat{p} = \frac{\vec{b} + \vec{c}}{ \vec{b} + \vec{c} } = \frac{(2+\lambda)\hat{i} + 6\hat{j} - 2\hat{k}}{\sqrt{(2+\lambda)^2 + 6^2 + (-2)^2}} = \frac{(2+\lambda)\hat{i} + 6\hat{j} - 2\hat{k}}{\sqrt{\lambda^2 + 4\lambda + 44}}$ $\therefore \frac{1}{\sqrt{\lambda^2 + 4\lambda + 44}} \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 1 & 1 \\ 2+\lambda & 6 & -2 \end{vmatrix} = \sqrt{2}$ $\Rightarrow  (-2-6)\hat{i} - \{-2-(2+\lambda)\}\hat{j} + \{6-(2+\lambda)\}\hat{k} $ $= \sqrt{2}\sqrt{\lambda^2 + 4\lambda + 44}$ $\Rightarrow  -8\hat{i} + (4+\lambda)\hat{j} + (4-\lambda)\hat{k}  = \sqrt{2}\sqrt{\lambda^2 + 4\lambda + 44}$ $\Rightarrow \sqrt{(-8)^2 + (4+\lambda)^2 + (4-\lambda)^2} = \sqrt{2}\sqrt{\lambda^2 + 4\lambda + 44}$ $\Rightarrow \lambda = 1 \text{ (after squaring on both sides)}$	1 1 1
<p style="text-align: center;">SECTION D (Each question carries 5 marks)</p>		

32.	<div data-bbox="386 191 641 430" data-label="Image"> </div> <p>Here, by triangle law of vector addition  <math>\vec{a} + \vec{b} = -\vec{c} \dots\dots\dots(i)</math>  By pre cross multiplication of (i) by <math>\vec{a}</math>, we get  <math>\vec{a} \times \vec{a} + \vec{a} \times \vec{b} = -\vec{a} \times \vec{c}</math>  <math>\Rightarrow \vec{a} \times \vec{b} = \vec{c} \times \vec{a} \dots\dots\dots(ii)</math>  By post cross multiplication of (i) by <math>\vec{b}</math>, we get  <math>\vec{a} \times \vec{b} + \vec{b} \times \vec{b} = -\vec{c} \times \vec{b}</math>  <math>\Rightarrow \vec{a} \times \vec{b} = \vec{b} \times \vec{c} \dots\dots\dots(iii)</math>  From (ii) and (iii)  <math>\vec{a} \times \vec{b} = \vec{b} \times \vec{c} = \vec{c} \times \vec{a}</math>  <math>\Rightarrow  \vec{a} \times \vec{b}  =  \vec{b} \times \vec{c}  =  \vec{c} \times \vec{a} </math>  <math>\Rightarrow  \vec{a}  \vec{b} \sin(\pi - C) =  \vec{b}  \vec{c} \sin(\pi - A) =  \vec{c}  \vec{a} \sin(\pi - B)</math>  <math>\Rightarrow ab \sin C = bc \sin A = ca \sin B</math>  Dividing by abc, we get <math>\frac{\sin A}{a} = \frac{\sin B}{b} = \frac{\sin C}{c}</math></p>	<p>0.5</p> <p>0.5</p> <p>1</p> <p>1</p> <p>2</p>
32.(OR)	<p>Here, <math> \vec{a} + \vec{b} ^2 =  \vec{a} ^2 +  \vec{b} ^2 + 2\vec{a} \cdot \vec{b}</math>  <math>= 1^2 + 1^2 + 2 \vec{a}  \vec{b} \cos\theta</math>  <math>= 1^2 + 1^2 + 2 \cdot 1 \cdot 1 \cdot \cos\theta</math>  <math>= 2 + 2\cos\theta = 2(1 + \cos\theta) = 2 \cdot 2\cos^2 \frac{\theta}{2} = 4\cos^2 \frac{\theta}{2}</math>  <math>\therefore  \vec{a} + \vec{b} ^2 = 4\cos^2 \frac{\theta}{2}</math>  <math>\Rightarrow  \vec{a} + \vec{b}  = 2\cos \frac{\theta}{2} \dots\dots\dots(i)</math>  And, <math> \vec{a} - \vec{b} ^2 =  \vec{a} ^2 +  \vec{b} ^2 - 2\vec{a} \cdot \vec{b}</math>  <math>= 1^2 + 1^2 - 2 \vec{a}  \vec{b} \cos\theta</math>  <math>= 1^2 + 1^2 - 2 \cdot 1 \cdot 1 \cdot \cos\theta</math>  <math>= 2 - 2\cos\theta = 2(1 - \cos\theta) = 2 \cdot 2\sin^2 \frac{\theta}{2} = 4\sin^2 \frac{\theta}{2}</math>  <math>\therefore  \vec{a} - \vec{b} ^2 = 4\sin^2 \frac{\theta}{2}</math>  <math>\Rightarrow  \vec{a} - \vec{b}  = 2\sin \frac{\theta}{2} \dots\dots\dots(ii)</math>  Dividing (ii) by (i)</p>	<p>2</p> <p>2</p> <p>1</p>

	$\tan \frac{\theta}{2} = \frac{ \vec{a} - \vec{b} }{ \vec{a} + \vec{b} }$	
33.	 <p>Equation of BC: <math>\frac{x-0}{2-0} = \frac{y+1}{-3+1} = \frac{z-3}{-1-3}</math> i.e. <math>\frac{x-0}{2} = \frac{y+1}{-2} = \frac{z-3}{-4} = \lambda</math>, with direction ratios <math>\langle 2, -2, -4 \rangle</math></p> <p>Now, coordinates of L point on the line BC are <math>(2\lambda, -2\lambda - 1, -4\lambda + 3)</math>.</p> <p>Thus, direction ratios of AL are <math>\langle 2\lambda - 1, -2\lambda - 1 - 8, -4\lambda + 3 - 4 \rangle</math> i.e. <math>\langle 2\lambda - 1, -2\lambda - 9, -4\lambda - 1 \rangle</math></p> <p>L is the foot of the perpendicular drawn from A on BC. Therefore, AL is perpendicular to BC.</p> <p>So, we have <math>2(2\lambda - 1) + (-2)(-2\lambda - 9) + (-4)(-4\lambda - 1) = 0</math>.  <math>\Rightarrow 4\lambda - 2 + 4\lambda + 18 + 16\lambda + 4 = 0</math>  <math>\Rightarrow 24\lambda + 20 = 0 \Rightarrow \lambda = \frac{-5}{6}</math></p> <p>Hence, <math>L = (2\lambda, -2\lambda - 1, -4\lambda + 3) = \left(2\left(\frac{-5}{6}\right), -2\left(\frac{-5}{6}\right) - 1, -4\left(\frac{-5}{6}\right) + 3\right) = \left(\frac{-5}{3}, \frac{2}{3}, \frac{19}{3}\right)</math></p> <p>The length of the perpendicular</p> $AL = \sqrt{\left(1 + \frac{5}{3}\right)^2 + \left(8 - \frac{2}{3}\right)^2 + \left(4 - \frac{19}{3}\right)^2} = \frac{\sqrt{597}}{3}$ <p>If <math>A'(a, b, c)</math> be the image of <math>A(1, 8, 4)</math> in the line through B and C, then L is the mid point of <math>AA'</math></p> <p>Therefore, <math>\frac{-5}{3} = \frac{1+a}{2}, \frac{2}{3} = \frac{8+b}{2}, \frac{19}{3} = \frac{4+c}{2}</math>  <math>\Rightarrow a = \frac{-13}{3}, b = \frac{-20}{3}, c = \frac{26}{3}</math></p> <p>Hence, <math>A' = \left(\frac{-13}{3}, \frac{-20}{3}, \frac{26}{3}\right)</math></p>	1  1  1  1
33.(OR)		1

	<p> <math display="block">L: \frac{x}{1} = \frac{y-1}{2} = \frac{z-2}{3} = \lambda, \quad \text{with direction ratios } \langle 1, 2, 3 \rangle</math> </p> <p>Coordinates of any point M on the L i.e. <math>M = (\lambda, 2\lambda + 1, 3\lambda + 2)</math>.</p> <p>Now, direction ratios of line PM are <math>\langle \lambda - 1, 2\lambda + 1 - 6, 3\lambda + 2 - 3 \rangle</math>  i.e. <math>\langle \lambda - 1, 2\lambda - 5, 3\lambda - 1 \rangle</math></p> <p>If M is the foot of the perpendicular drawn from P on the line L.  Then PM is perpendicular to L</p> <p> <math display="block">\therefore 1(\lambda - 1) + 2(2\lambda - 5) + 3(3\lambda - 1) = 0</math> </p> <p> <math display="block">\Rightarrow 14\lambda - 14 = 0 \Rightarrow \lambda = 1</math> </p> <p>Hence, <math>M = (\lambda, 2\lambda + 1, 3\lambda + 2) = (1, 3, 5)</math></p> <p>Let Q(a, b, c) be the image of P(1, 6, 3) in the line L (but on the line <math>L_2</math>).  Then, M is the mid-point of PQ  (as object distance from the mirror is equal to the image distance from the mirror)</p> <p>Therefore, <math>1 = \frac{1+a}{2}, 3 = \frac{6+b}{2}, 5 = \frac{3+c}{2}</math></p> <p> <math display="block">\Rightarrow a = 1, b = 0, c = 7</math> </p> <p>Thus, a point on the line <math>L_2</math> is Q(1, 0, 7)</p> <p>Hence the equation of the line <math>L_2</math> is <math>\frac{x-1}{1} = \frac{y}{2} = \frac{z-7}{3}</math> (since the lines are parallel, direction ratios remain same)</p>	<p>1</p> <p>1</p> <p>1</p> <p>1</p>
34.	<p>Given lines are</p> <p> <math display="block">L_1: \vec{r} = (1-t)\hat{i} + (t-2)\hat{j} + (3-2t)\hat{k}</math> <math display="block">= \hat{i} - t\hat{i} + t\hat{j} - 2\hat{j} + 3\hat{k} - 2t\hat{k}</math> <math display="block">= (\hat{i} - 2\hat{j} + 3\hat{k}) - t(\hat{i} - \hat{j} + 2\hat{k}).</math> </p> <p> <math display="block">L_2: \vec{r} = (s+1)\hat{i} + (2s-1)\hat{j} - (2s+1)\hat{k}.</math> <math display="block">= s\hat{i} + \hat{i} + 2s\hat{j} - \hat{j} - 2s\hat{k} - \hat{k}.</math> <math display="block">= (\hat{i} - \hat{j} - \hat{k}) + s(\hat{i} + 2\hat{j} - 2\hat{k})</math> </p> <p>Now, <math>\vec{a}_2 - \vec{a}_1 = (\hat{i} - \hat{j} - \hat{k}) - (\hat{i} - 2\hat{j} + 3\hat{k}) = 0\hat{i} + \hat{j} - 4\hat{k}</math></p> <p>Also, <math>\vec{b}_1 \times \vec{b}_2 = \begin{vmatrix} \hat{i} &amp; \hat{j} &amp; \hat{k} \\ 1 &amp; -1 &amp; 2 \\ 1 &amp; 2 &amp; -2 \end{vmatrix} = \hat{i}(2-4) - \hat{j}(-2-2) + \hat{k}(2+1)</math></p> <p> <math display="block">= -2\hat{i} + 4\hat{j} + 3\hat{k}.</math> </p> <p>Hence, shortest distance between two lines <math>L_1</math> and <math>L_2 = \left  \frac{(\vec{a}_2 - \vec{a}_1) \cdot (\vec{b}_1 \times \vec{b}_2)}{ \vec{b}_1 \times \vec{b}_2 } \right </math></p> <p> <math display="block">= \left  \frac{0 \cdot (-2) + 1 \cdot 4 + (-4) \cdot 3}{\sqrt{(-2)^2 + 4^2 + 3^2}} \right  = \frac{8}{\sqrt{29}} \text{ units.}</math> </p>	<p>1</p> <p>1</p> <p>1</p> <p>2</p>





	<p>Hence, (i) <math>\Rightarrow P = 1000 e^{kt} \dots\dots\dots(ii)</math></p> <p>Again, at <math>t=1, P=2000</math></p> <p>In this case, (ii) <math>\Rightarrow 2000 = 1000 e^k</math></p> <p><math>\Rightarrow 2 = e^k \therefore k = \log 2</math></p>	
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